Being Smart About Al



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Berkeley





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Charles Isbell

Georgia Tech



Jim Kurose

OSTP & NSF



This is where the AI business is at right now...

...but we should also consider how we understand and empower humans...

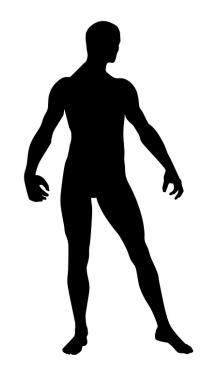
...and what it's like to live and work in an Al-driven world...

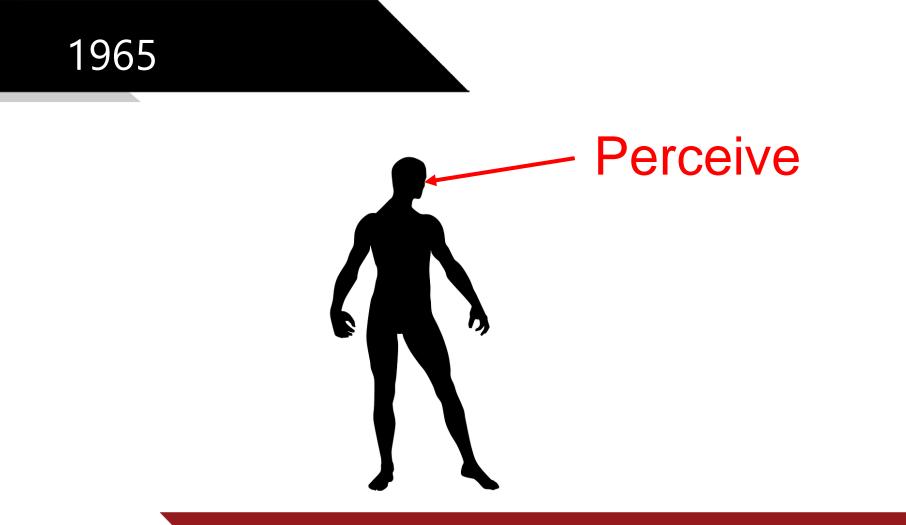
.....because it can go so wrong if done wrong but so right if done right...

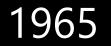


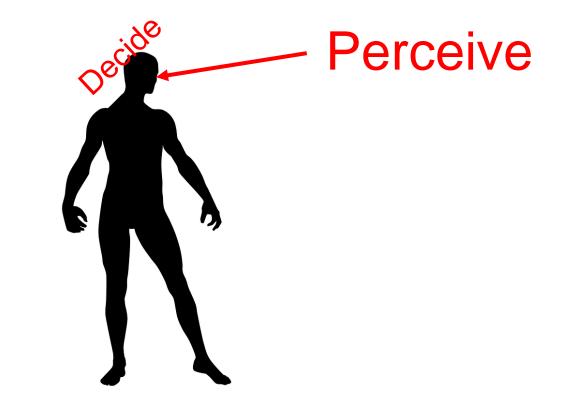
...and so at NSF we are investing strategically in AI.

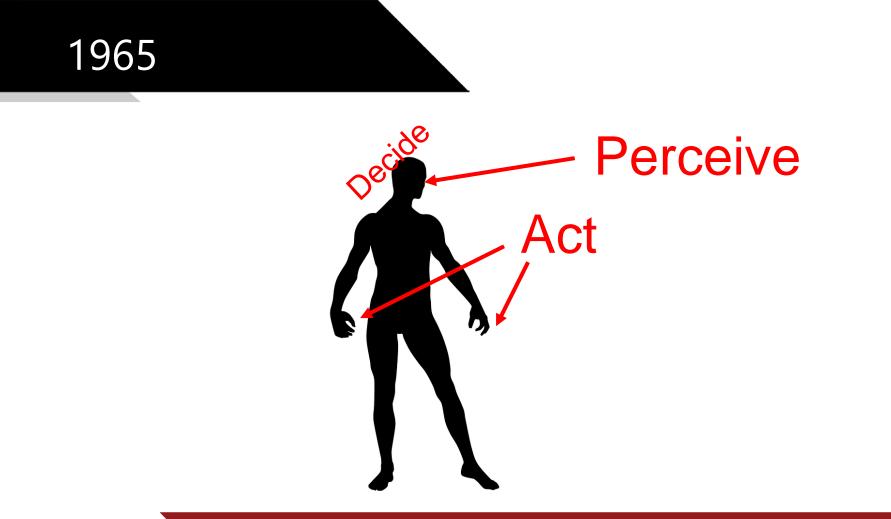






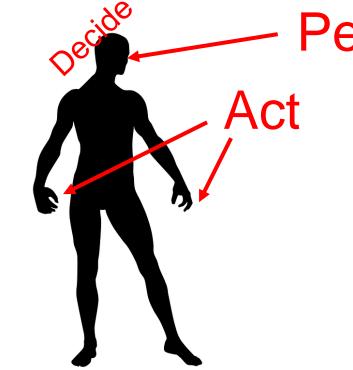






1997 Kasparov Defeat



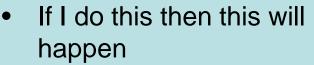


- Perceive



How Decide Works

Decide



- But if I do that then this other thing will happen
- Or if I do this third option...
 How do I predict the effects of How do I predict the effects of each action?

1997: Predicting effects

Decide

Software Engineers write a set of Rules that predict the effects

How do I predict the effects of each action?

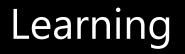
2003: Predicting effects

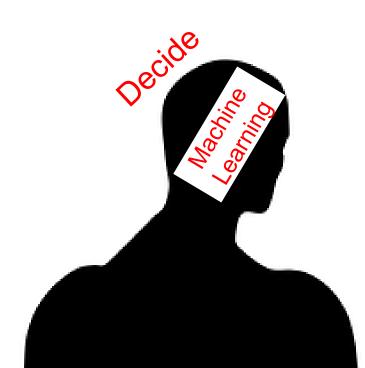
Decide

Machine

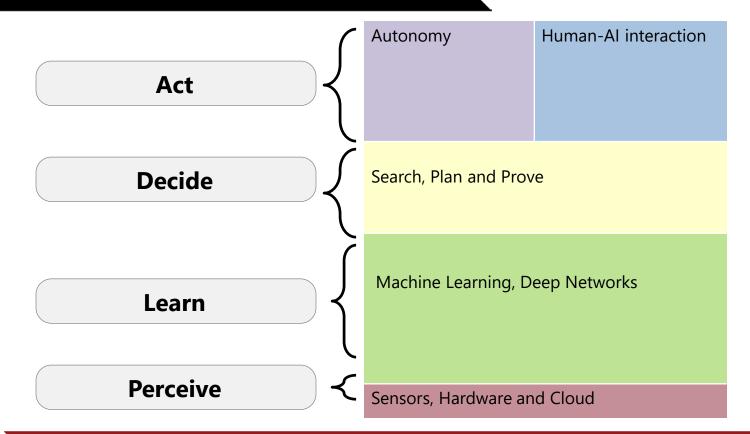
Learn to predict by extrapolating from previous data

How do I predict the effects of each action?

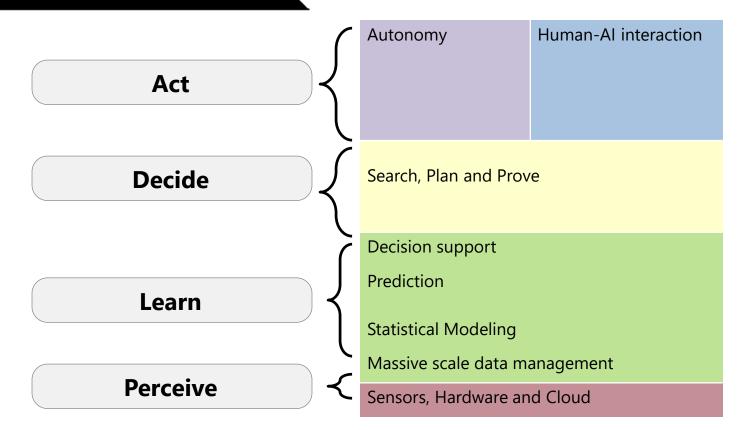




The AI Technology Stack



The AI Stack



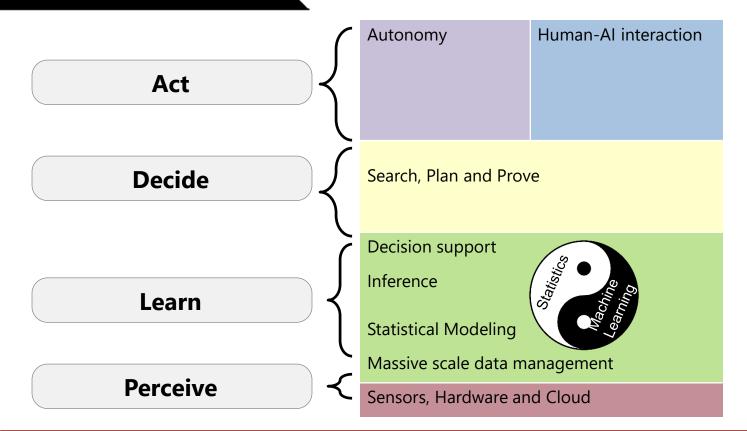


Machine Learning

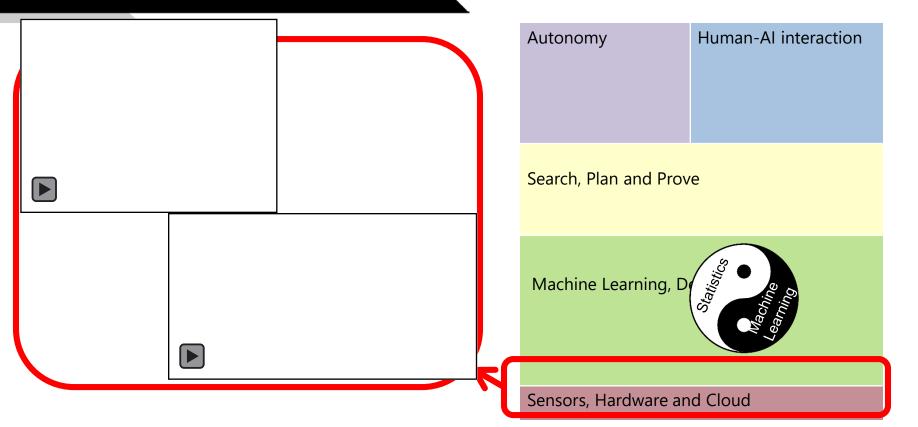
Statistics

A

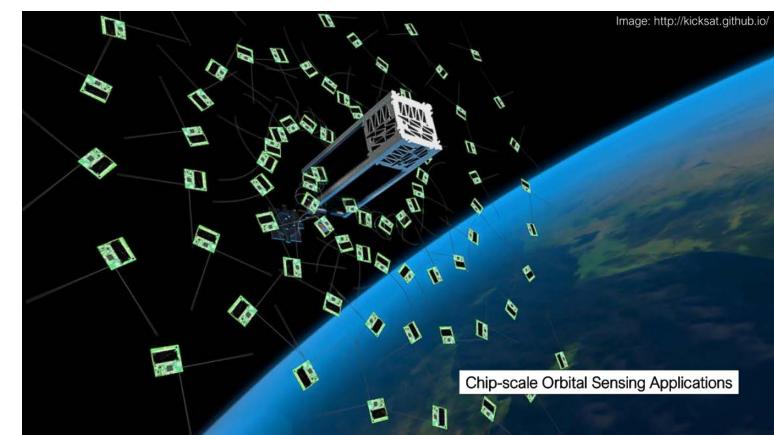
The AI Stack



The AI Stack



1 mA neural network image detection



The AI Stack

Video unsupported

Autonomy	Human-Al interaction	
Search, Plan and Prove		
Machine Learning, D		
Sensors, Hardware and Cloud		

Michael Kaess

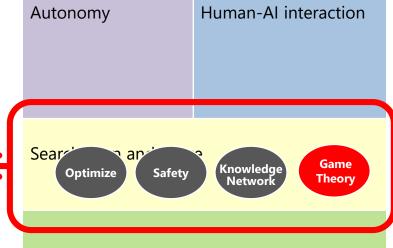
Safety



Autonomy	Human-Al interaction	
Search, Plan and Prove		
Machine Learning, Deep Networks		

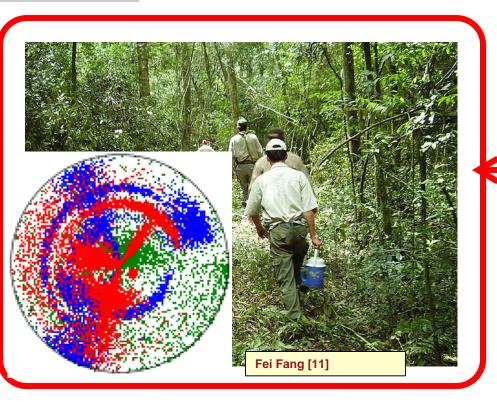
Negotiation & Deception

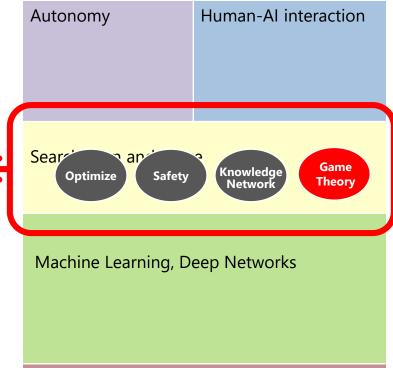




Machine Learning, Deep Networks

Negotiation & Surveillance





Human-Al



Henny Admoni

Autonomy

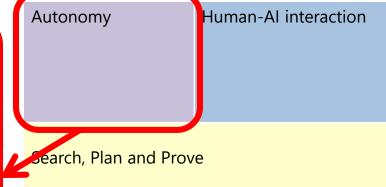
Search, Plan and Prove

Machine Learning, Deep Networks

Human-Al interaction

Autonomy



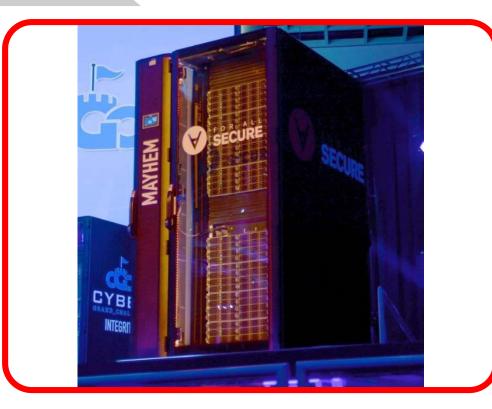


Machine Learning, Deep Networks

Sensors, Hardware and Cloud

Leidos (autonomy by CMU)

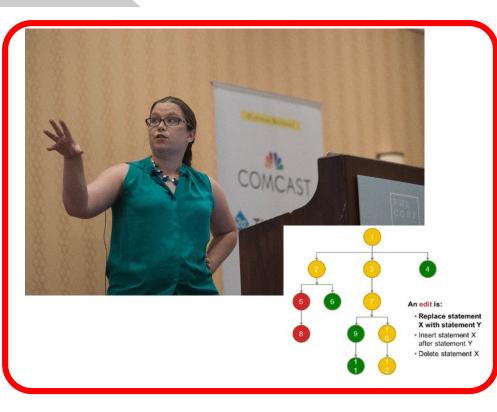
Autonomy

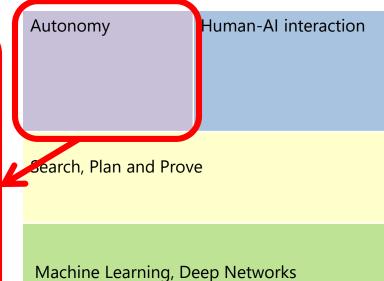


Autonomy	Human-Al interaction
Search, Plan and Prov	e

Machine Learning, Deep Networks

Autonomy





3. 1



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...and what it's like to live and work in an Al-driven world...

.....because it can go so wrong if done wrong but so right if done right...



...and so at NSF we are investing strategically in AI.

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 Iris Recognition: https://www.cylab.cmu.edu/partners/success-stories/iris-recognition.html
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 - Using voice recognition to identify characteristics and surroundings: http://www.csoonline.com/article/3112752/techology-business/voice-technologies-makewaves-in-security.html
- [5] Fernando de La Torre, Takeo Kanade, Jeff Cohn, Simon Lucey | slucey@cs.cmu.edu | Associate Research Professor, Robotics Institute & Director, Cl2CV Computer Vision Lab: http://www.cs.cmu.edu/~Cl2CV/

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- [6] Artur Dubrawski | awd@andrew.cmu.edu | Senior Systems Scientist, Robotics Institute • Marinus Analytics: <u>http://www.marinusanalytics.com/,</u> <u>http://www.cmu.edu/news/stories/archives/2015/january/detecting-sex-traffickers.html</u>
- [7] **Tuomas Sandholm** | <u>sandholm@cs.cmu.edu</u> | *Professor, Computer Science Department & Director, Electronic Marketplaces Laboratory*
 - Using algorithms to match live kidney donors with recipients: https://www.cmu.edu/news/archive/2010/November/nov16_kidneyalgorithm.shtml
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- [7c] André Platzer | aplatzer@cs.cmu.edu | Associate Professor, Computer Science Department
 KeYmaera: A Hybrid Theorem Prover for Hybrid Systems: http://symbolaris.com/info/KeYmaera.html

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CMU Wins Cyber Attack Challenge:

http://www.cmu.edu/news/stories/archives/2016/august/cyber-attack-challenge-winner.html • Paper: Using MAYHEM on Binary Code: https://users.ece.cmu.edu/~arebert/papers/mayhemoakland-12.pdf

[9] L.P. Morency and 15-112 students

Jen Mankoff | jmankoff@cs.cmu.edu | Professor, Human-Computer Interaction Institute • Crowd-sourced prosthetics; Giving a Hand to Those in Need: https://www.hcii.cmu.edu/news/2016/giving-hand-those-need

Howie Choset | choset@cs.cmu.edu | Associate Professor, Robotics Institute

- Medrobotics: <u>http://medrobotics.com/</u>
- Highly Articulated Robotics Probe for Minimally Invasive Surgery: https://www.ncbi.nlm.nih.gov/pmc/articles/PMC2923469
- [10] Claire Legoues: Automatic Bug Detection https://clairelegoues.com/

[11] Fei Fang---game theory against poaching, logging and mining https://feifang.info/research/

- [12] User See, User Point: Gaze and Cursor Alignment in Web Search Jeff Huang, Ryen W. White, Georg Buscher CHI 2012
- [13] https://news.brown.edu/articles/2017/08/surveilliance
- [14] https://www.cs.cmu.edu/~mfredrik/papers/fredrikson-usenix14-genomic.pdf

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[16] Sandholm and Brown, CMU CS, http://www.cs.cmu.edu/~sandholm/safeAndNested.aaa17WS.pdf

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